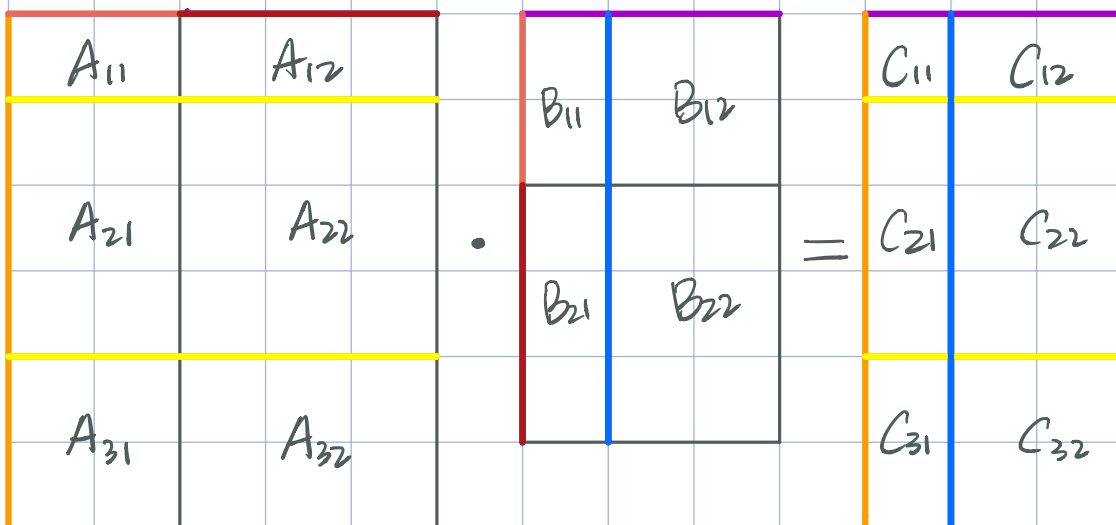


More generally:



$$C_{11} = A_{11}B_{11} + A_{12}B_{21}$$

$$C_{12} = A_{11}B_{12} + A_{12}B_{22}$$

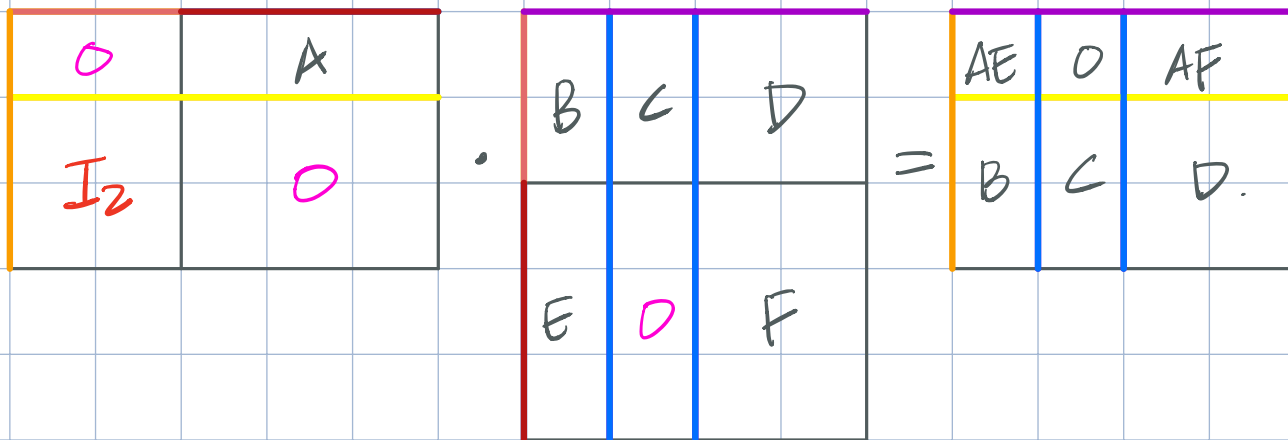
$$C_{21} = A_{21}B_{11} + A_{22}B_{21}$$

$$C_{22} = A_{21}B_{12} + A_{22}B_{22}$$

$$C_{31} = A_{31}B_{11} + A_{32}B_{21}$$

$$C_{32} = A_{31}B_{12} + A_{32}B_{22}$$

E.g.



this means for each  $v$  in  $V$  we assign a unique  $T(v)$  in  $W$

**Def.** Let  $V, W$  be vector spaces over  $\mathbb{R}/\mathbb{C}$ , a map  $T: V \rightarrow W$  is called a **linear transformation** if for any  $v, v'$  in  $V$  and  $\lambda$  in  $\mathbb{R}/\mathbb{C}$ :

- Scalar multiplications are preserved:  $T(\lambda \cdot v) = \lambda \cdot T(v)$
  - Additions are preserved:  $T(v + v') = T(v) + T(v')$
- as vectors in  $W$ .

★ The 2 conditions are equivalent to the condition that linear combinations are preserved.

**Eg's ?**

Trivial ones:

vector space of linear transformations from  $V$  to  $W$

1. **Zero map**  $0$ : send everything to the **zero vector** in  $W$

2. **Identity map**  $\text{id}: V \rightarrow V$ : does nothing,  $\text{id}(v) = v$  for all  $v$

Interesting ones: sometimes also write  $\text{id}_V$  to indicate it's the identity map on  $V$ .

1. Differentiation:

$\{\text{differentiable } \mathbb{R}\text{-valued functions}\} \rightarrow \{\mathbb{R}\text{-valued functions}\}$

2.  $\int_a^x$ : some fixed real number

$\{\text{integrable } \mathbb{R}\text{-valued functions}\} \rightarrow \{\text{differentiable } \mathbb{R}\text{-valued functions}\}$

$$f(x) \mapsto \int_a^x f(t) dt$$

★ When  $T: V \rightarrow W$  is a linear transformation, we have:

$$1. T(0_V) = 0_W \quad (T(0_V) = T(0 \cdot 0_V) = 0 \cdot T(0_V))$$

$$2. T(-v) = -T(v)$$

$$(T(-v) = T((-1)v) = (-1) \cdot T(v) = -T(v))$$

in  $\mathbb{R}/\mathbb{C}$

Exercise: A linear transformation  $V \rightarrow W$  is determined by what it does on any subset  $S$  of  $V$  that spans  $V$ .

$S = \{v_1, v_2\}$ ,  $\text{span } S = V$ ,  $T: V \rightarrow W$ ,  $T(v_1), T(v_2)$  known

$$v = a_1 v_1 + a_2 v_2$$

$$T(v) = T(a_1 v_1 + a_2 v_2) = a_1 T(v_1) + a_2 T(v_2)$$

$T(v)$  is determined for all  $v$  in  $V$ .

E.g. Let  $V$  be 2-dimensional vector space with basis  $\{v_1, v_2\}$ ,

$W$  be a 3-dimensional vector space with basis  $\{w_1, w_2, w_3\}$ ,

then a linear transformation  $T: V \rightarrow W$  is determined

by  $T(v_1), T(v_2)$ , but

$$T(v_1) = a_{11} w_1 + a_{21} w_2 + a_{31} w_3 \quad \text{for some } a_{11}, a_{21}, a_{31},$$

$$T(v_2) = a_{12} w_1 + a_{22} w_2 + a_{32} w_3 \quad a_{12}, a_{22}, a_{32} \text{ in } \mathbb{R}$$

In other words,  $T$  is represented by the matrix  $\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{pmatrix}$

In general, when  $V$  is an  $m$ -dimensional vector space

with basis  $\mathcal{X}$ ,  $W$  is an  $n$ -dimensional vector space

with basis  $\mathcal{Y}$ , a linear transformation  $T: V \rightarrow W$  is

represented by an  $n \times m$  matrix  $[T]_{\mathcal{Y}\mathcal{X}}$  (depends on the choice of bases)

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